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# LINEAR CONTROL SYSTEMS

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# Lecture 1

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## An Introduction to Linear Control Systems

*Topics to be covered include:*

- ❖ About the Course
- ❖ Introduction.
- ❖ Some Advanced Control System.
- ❖ Different Parts of Control Systems.
- ❖ Open-loop and Closed-loop systems.
- ❖ Feedback Property

# Syllabus

- ❖ An Introduction to Linear Control Systems.(Lecture 1)
  - ❖ Different Representations of Control Systems and Linearization.(Lecture 2)
  - ❖ Internal and External Description. (Tf and SS Description). (Lecture 3)
  - ❖ Stability Analysis. (Lecture 4)
  - ❖ Time Domain Analysis of Control Systems. (Lecture 5)
  - ❖ Root Locus Criteria. (Lecture 6)
  - ❖ Controller Design in the Time Domain. (Lecture 7)
  - ❖ Frequency Domain Analysis of Control Systems.(Lecture 8)
  - ❖ Nyquist Stability Criteria. (Lecture 9)
  - ❖ Controller Design in the Frequency Domain. (Lecture 10)
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- The diagram consists of three vertical pink brackets on the right side of the slide, each grouping a set of lectures. The first bracket, labeled 'A' in a purple circle, groups Lectures 1 through 4. The second bracket, labeled 'B' in a purple circle, groups Lectures 5 through 7. The third bracket, labeled 'C' in a purple circle, groups Lectures 8 through 10.

# Prerequisite and Grading

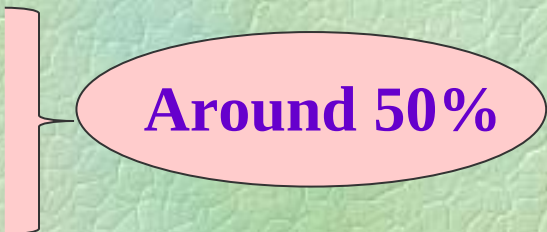
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## Prerequisite

- ❖ English Knowledge, Primary Mathematics, MATLAB Software

## Grading

- ❖ Quizzes (Important part).
- ❖ Class works(Important part).
- ❖ Midterms.
- ❖ Final.



**Around 50%**

# References

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- ❖ **Modern Control Systems (12th Edition) By Richard C. Dorf , Robert H. Bishop.**
- ❖ **Automatic Control Systems (9th Edition) By Farid Golnaraghi, Benjamin C. Kuo.**
- ❖ **Control Systems Engineering (Wiley 2000) By Norman S. Nise**

# Introduction

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**Control System** An interconnection of components forming a system configuration that will provide a desired response.

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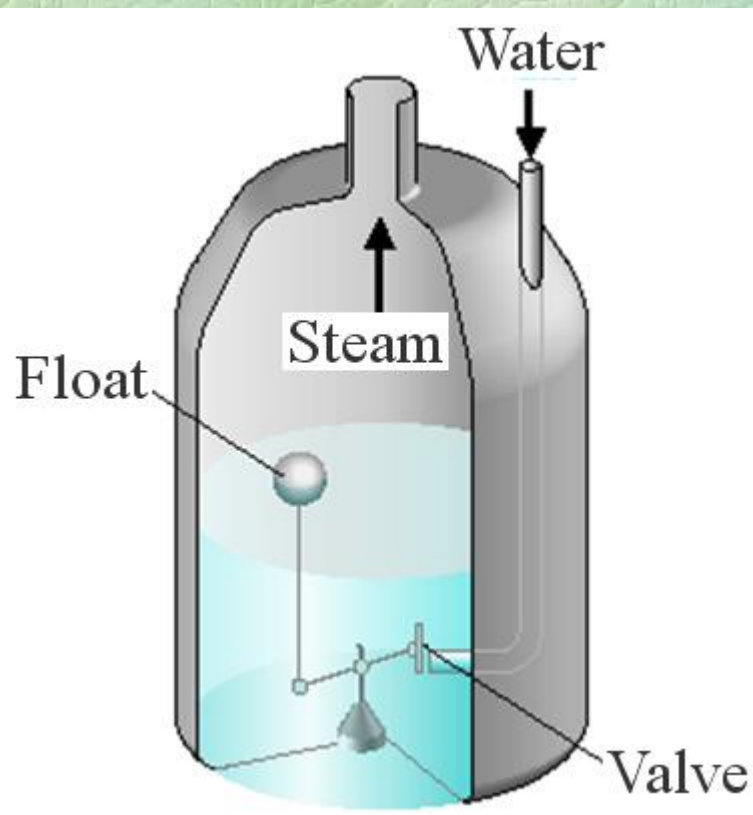
## Different Parts of a Control System

- ❖ System or Plant
- ❖ Objective
- ❖ States
- ❖ Output
- ❖ Input
- ❖ Sensors
- ❖ Actuators
- ❖ Computing
- ❖ Disturbance, noise & uncertainties

# Introduction - History of Control Engineering

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Water-level float regulator  
(before BC)

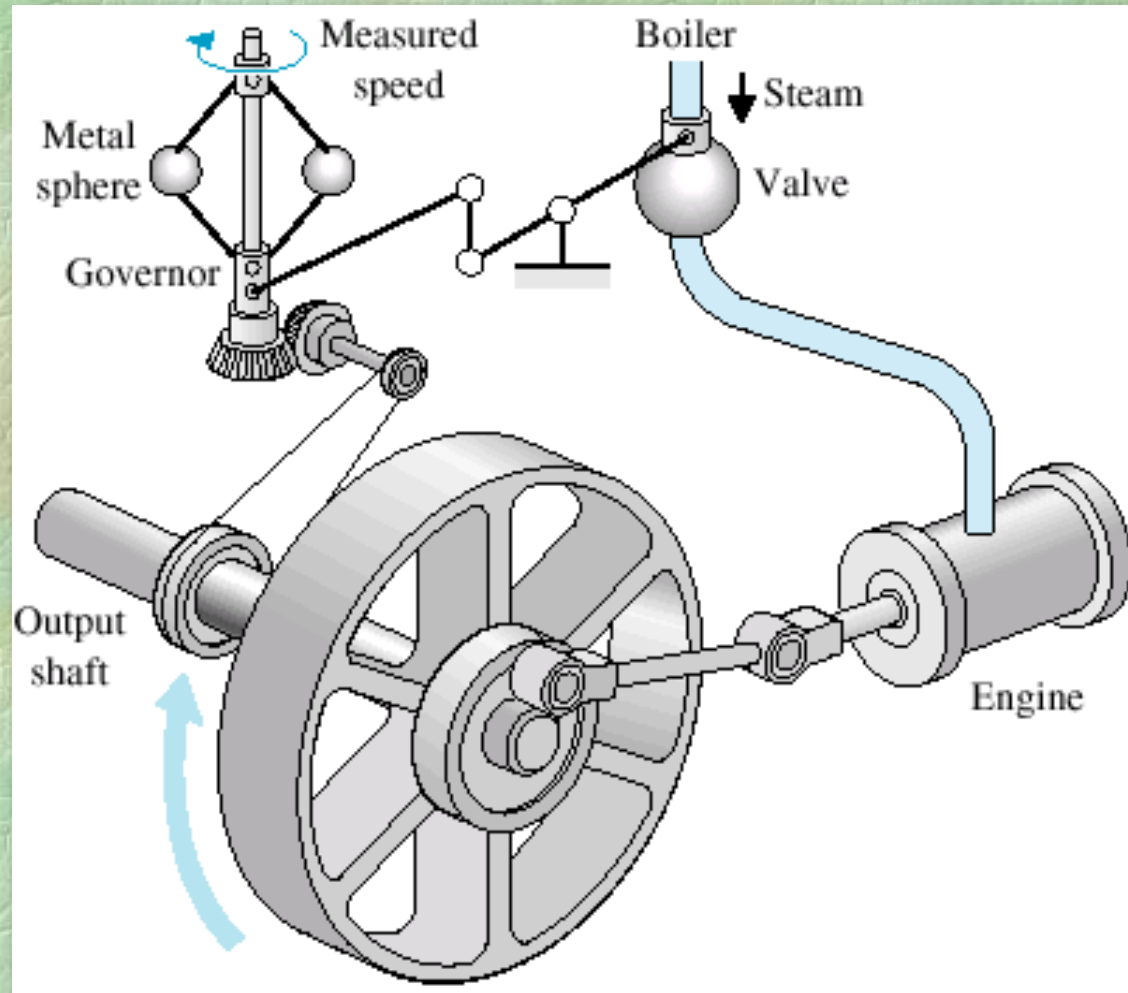


RQ-170 unmanned plane  
(Nowadays)



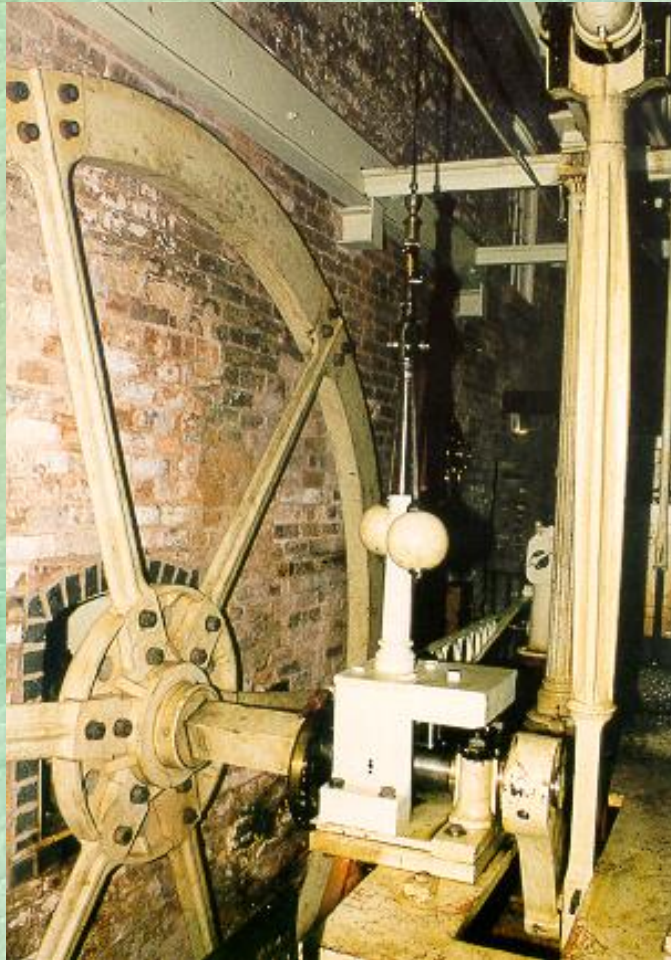
# Introduction - History of Control Engineering

**18th Century** James Watt's centrifugal governor for the speed control of a steam engine.



# Introduction - History of Control Engineering

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This photograph shows a **flyball governor** used on a **steam engine** in a cotton factory near Manchester in the United Kingdom. Actually, this cotton factory is still running today.

# Introduction - Earliest Control Systems?

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## Human System

- i. Pancreas
  - + Regulates blood glucose level
- ii. Adrenaline
  - + Automatically generated to increase the heart rate and oxygen in times of flight
- iii. Eye
  - + Follow moving object
- iv. Hand
  - + Pick up an object and place it at a predetermined location
- v. Temperature
  - + Regulated temperature of 36°C to 37°C

# Introduction

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## Some Control benefits

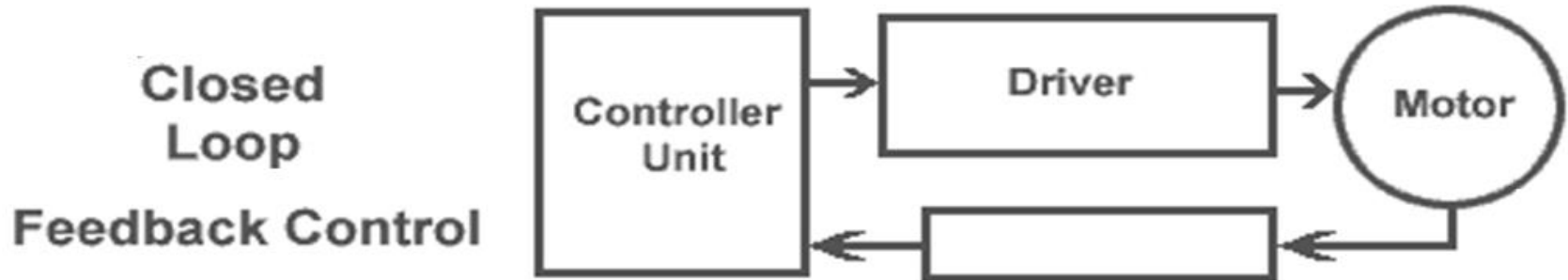
- ❖ Enhanced Product Quality.
- ❖ Waste Minimization.
- ❖ Environmental Protection.
- ❖ Greater Throughput for a Given Installed Capacity.
- ❖ Higher Safety Margins.

# Introduction - Control System Classification

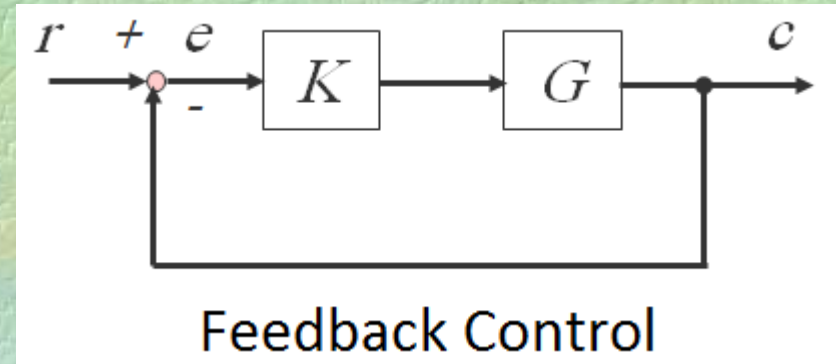
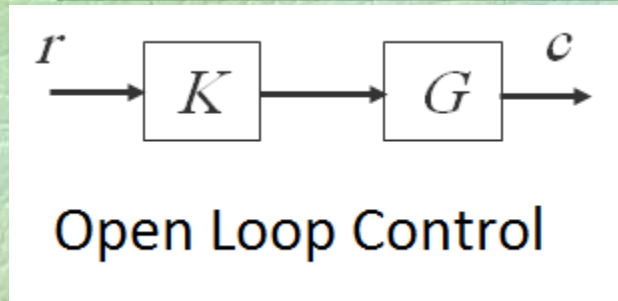
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1- Open Loop Control.

2- Closed Loop Control(Feedback).



# Introduction – Feedback Properties



## 1- Feedback Advantages:

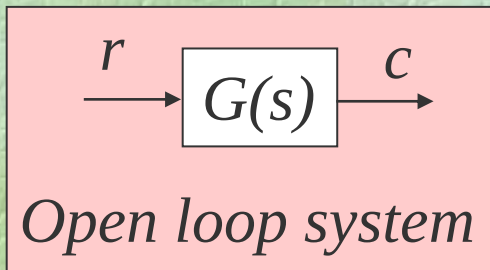
- ❖ Error reduction
- ❖ Gain regulation
- ❖ Sensitivity reduction
- ❖ Stabilization

## 2- Feedback Disadvantages:

- ❖ Speed reduction

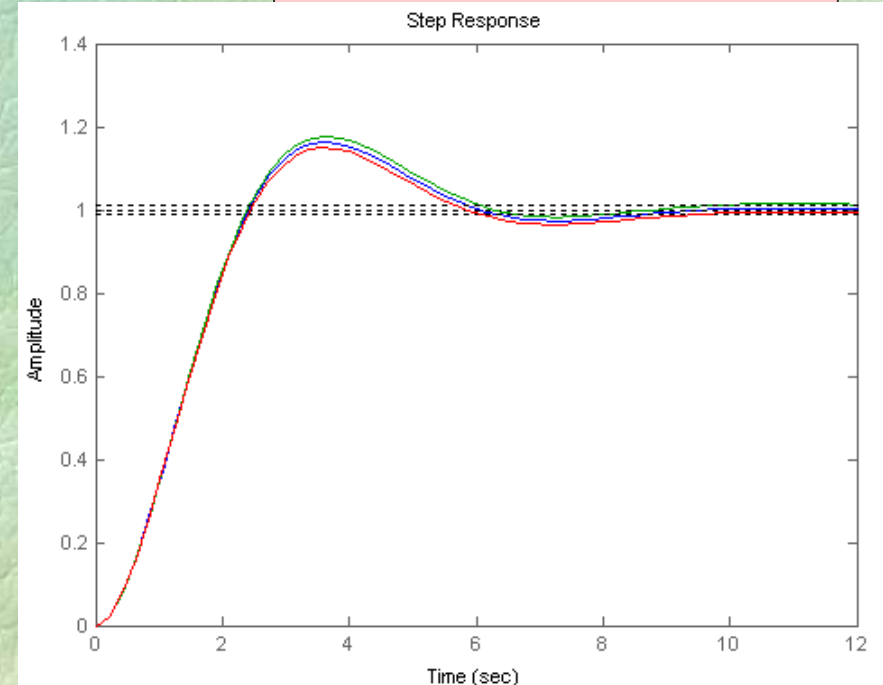
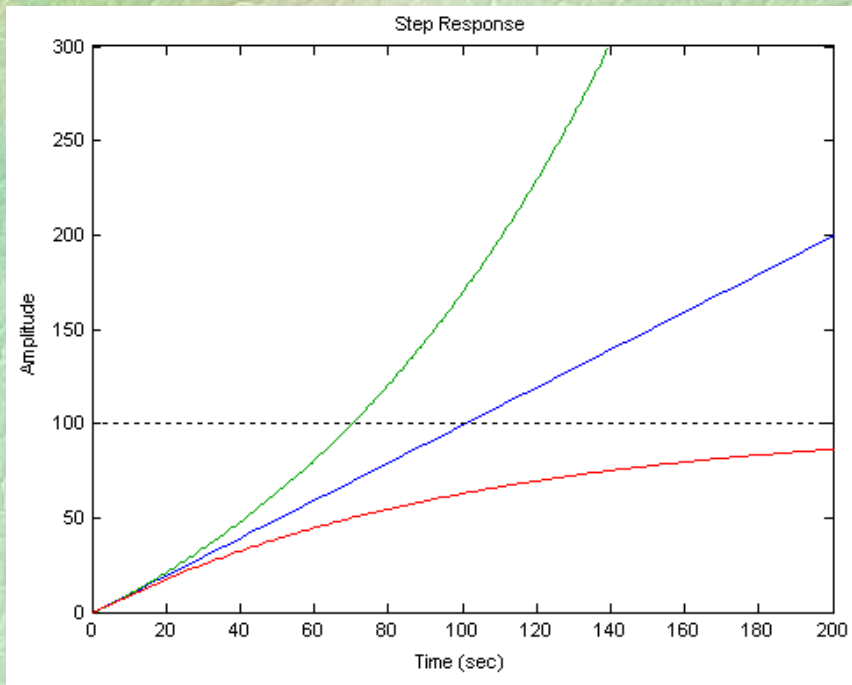
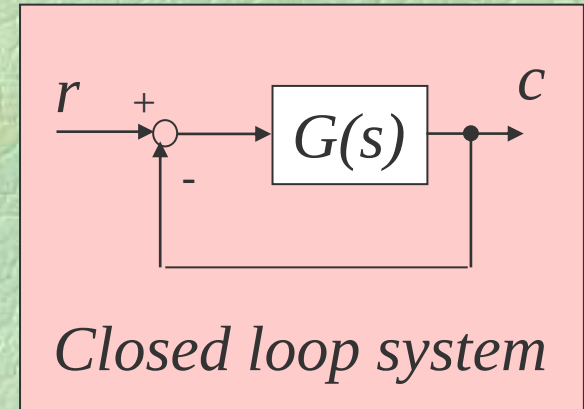
# Feedback properties

Example 1: Derive step response of following system in open loop and closed loop.



$$G(s) = \frac{1}{(s+1)(s+a)}$$

$$a = -0.01, 0, 0.01$$



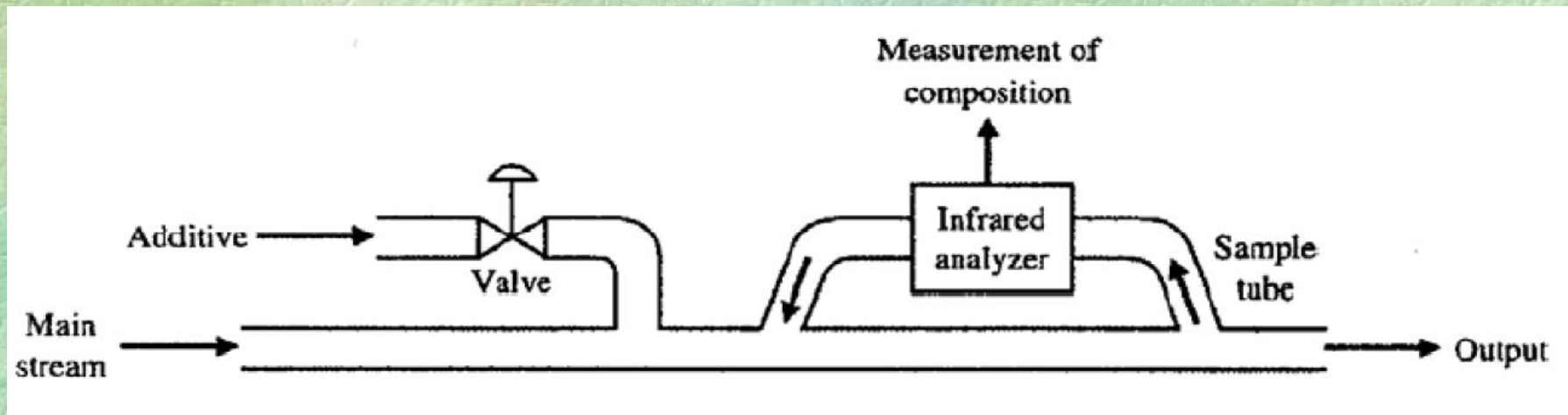
# When is the open loop representation applicable?

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- ❖ The model on which the design of the controller has been based is a very good representation of the plant,
- ❖ The model must be stable, and
- ❖ Disturbances and initial conditions are negligible.

# Exercises

1-1 In a control system of an industrial composition process, it is very important to control the chemical composition of the output. There is an infrared analyzer for measurement and the valve of additive stream is controllable. Explain different elements of system.



1-2 Describe a control system and explain different elements of system.